**Ros wiki tutorials :** <http://wiki.ros.org/ROS/Tutorials>

Refer Morgan Quigley as well

QSTP: <https://github.com/hardesh/QSTP-Introduction_to_ROS>

**Python resource :** <https://github.com/hardesh/QSTP-Introduction_to_ROS/tree/master/Week_1>

**Matlab** : Matlab on-ramp, Simulink on-ramp, Simscape tutorials from YouTube <https://www.youtube.com/playlist?list=PLn8PRpmsu08qZutTT-7dRthkAnFuQjCOV>

**Eagle :** Jeremy Blum Videos from YouTube <https://www.youtube.com/playlist?list=PL868B73617C6F6FAD>

**Robotics courses :** <https://www.edx.org/course/robotics-columbiax-csmm-103x-3>

**Rhoeby GitHub repo :** <https://github.com/Rhoeby/hexapod_ros>

**Neuropod GitHub repo :** <https://github.com/neuroprod/InsectRobotSimulation>

**NPTEL IIT KGP Robotics course :**

<https://www.youtube.com/playlist?list=PLbRMhDVUMngcdUbBySzyzcPiFTYWr4rV_>

**Alex Winkler** : [Alex's](https://www.alex-winkler.com/)

**Legged Robotics resources** : [Legged Robotics](https://pab47.github.io/legs.html#)